Genary Navigation Corp.

GN-150 INS/GPS

The **GN-150** is an excellent, small size, low weight and MEMS silicon-based Inertial Measurement Unit (IMU) integrated with next-generation GPS for control and navigation applications. It provides a wide range of output modes and advanced settings for specific usage scenarios.

GN-150 has an embedded navigation computer that runs a real-time Kalman filter providing drift-free, inertial data and 3-D orientation data. **GN-150** is sealed enclosure ensures long, trouble-free life and performance over full altitude and temperature range without risk of moisture contamination.



Highlights

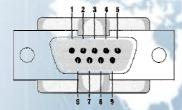
- Kalman-filter algorithms provided
- Full INS and attitude solution
- Embedded navigation computer and AHRS
- Misalignment, temperature and sensor cross-sensitivity calibrated
- Easy installation in any system application
- Next-generation RF technology (support GPS and Galileo)
- Digital output
- Compact, robust and water-proof design
- Low weight and low power consumption

Output

- Position coordinates, time,
- Heading, Pitch/Roll attitude angle

Applications

- UAV and Target Drone
- Marine Dynamics
- Autonomous vehicles
- Antenna Stabilization
- Attitude Reference
- Train & Container Tracking



Connector pins definition

| Pin | Signal | |
|-----|----------------------------|--|
| 1 | Digital Transmit data | |
| 2 | Digital Receive data | |
| 3 | Positive power input (+Vc) | |
| 4 | Power ground | |
| 5 | Chassis ground | |
| 6 | GPS Tx | |
| 7 | GPS Rx | |
| 8 | Signal ground | |
| 9 | 1 PPS out | |

GN-150 Specification

| Sensors | Gyroscope | Accelerometer | |
|--|--|---------------|--|
| Full scale | ±300°/sec | ±18 g | |
| In run bias stability | 25°/hr (1σ) | 0.2 mg (1σ) | |
| Operation range | | | |
| Heading | 0°~360° | | |
| Pitch | ±90° | | |
| Roll | ±180° | | |
| Altitude | 18,000 m | | |
| Velocity | 1,854 km/hr (~1000 knots) | | |
| Accuracy | | | |
| Heading | <1° | | |
| Pitch/Roll | <0.5° | | |
| Position accuracy | 2.0 m CEP (SBAS), 2.5 m CEP autonomous | | |
| Velocity accuracy | 0.1 m/s (50% @ 30 m/s) | | |
| Time accuracy (1PPS) | 30 ns | | |
| GPS receiver | | | |
| Receiver type | 50-channel, GPS L1, C/A code | | |
| Supports | SBAS (WASS, MSAS and EGNOS) | | |
| Navigation update rate | 1 Hz | | |
| Acquisition | Cold start 32 sec, Warm start 32 sec, Hot start < 3 sec, Aided start < 1 sec | | |
| I/O Interface | | | |
| Digital output | RS232 | | |
| Output sampling rate | 50 Hz (100 Hz for optional) | | |
| Baud rate | 9600 bps @ 50 Hz | | |
| Electrical | | | |
| Power input | 9 ~ 32 VDC | | |
| Power consumption | < 1.5 W | | |
| Start-up time | 35 sec | | |
| Environment | | | |
| Operation temperature | -40 ~ +85°C | | |
| Storage temperature | -40 ~ +85°C | | |
| Vibration | 5g, RMS (20~2000 Hz) | | |
| Shock 60g, 8ms 1/2 sine wave | | | |
| Physical OF The State of the Mark (1997) | | | |
| • Size | 85 mm × 65 mm × 50 mm (L × V | v × ⊓) | |
| Weight Connector | < 300 grams | | |
| Connector D-type 9-pin | | | |







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