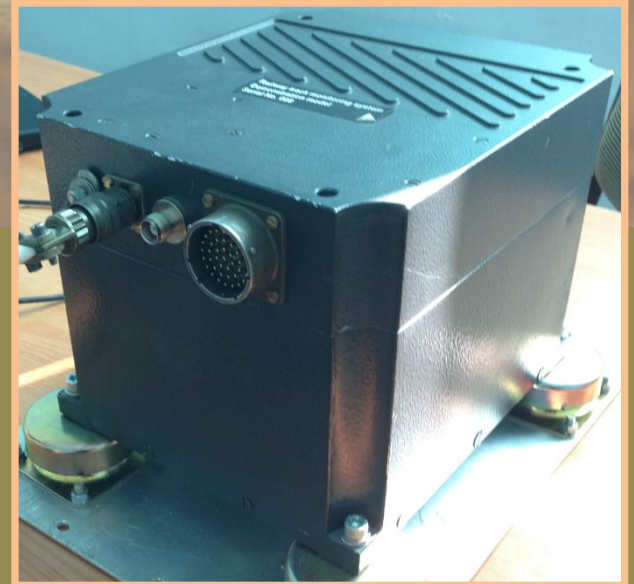


# LAND NAVIGATION SOLUTION



Strapdown Inertial Navigation System NAV9



# Performance

<b>Without GPS:</b>	
• Position, horizontal/vertical:	0.2% DT/0.15% DT
• Heading Stability (RMS):	0.5 mils/hr
• Roll, pitch (elevation):	<1.0 mils RMS
• Heading/Pointing Accuracy (azimuth):	<2.0 mils RMS
<b>Hybrid modes (horizontal/vertical position):</b>	
• INU, VMS, GPS SPS	0.10% of DT PE
• INU, VMS, GPS PPS	10m CEP/12m PE

# Characteristics

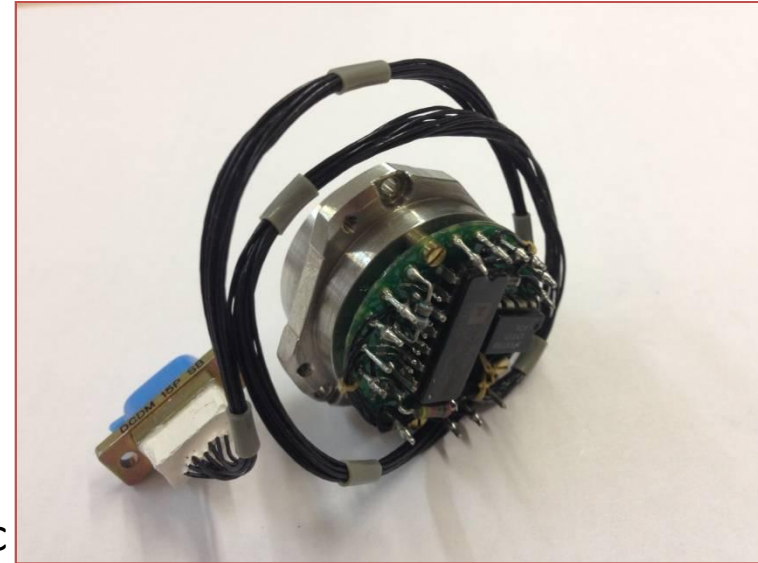
<b>General:</b>	<ul style="list-style-type: none"><li>• Attitude: Alignment and orientation in any direction</li><li>• Hard mounted</li><li>• Angular Rate: 300 deg/sec</li><li>• MTBF: &gt; 50000 hours</li></ul>
<b>Power requirements:</b>	<ul style="list-style-type: none"><li>• Power supply: 27 VDC,</li><li>• Consumption: &lt; 30 W</li></ul>
<b>Interfaces:</b>	<ul style="list-style-type: none"><li>• RS 422/232, CAN, Ethernet</li><li>• Optional: additional RS-422/RS-232</li><li>• Data rate: as per customer requirement</li></ul>
<b>Overall Features:</b>	<ul style="list-style-type: none"><li>• Size: 151 mm x 173 mm x 210 mm</li><li>• Weight: &lt; 5 kg</li><li>• No cooling required: -50°C to +71°C</li></ul>

# LG Performance Specifications

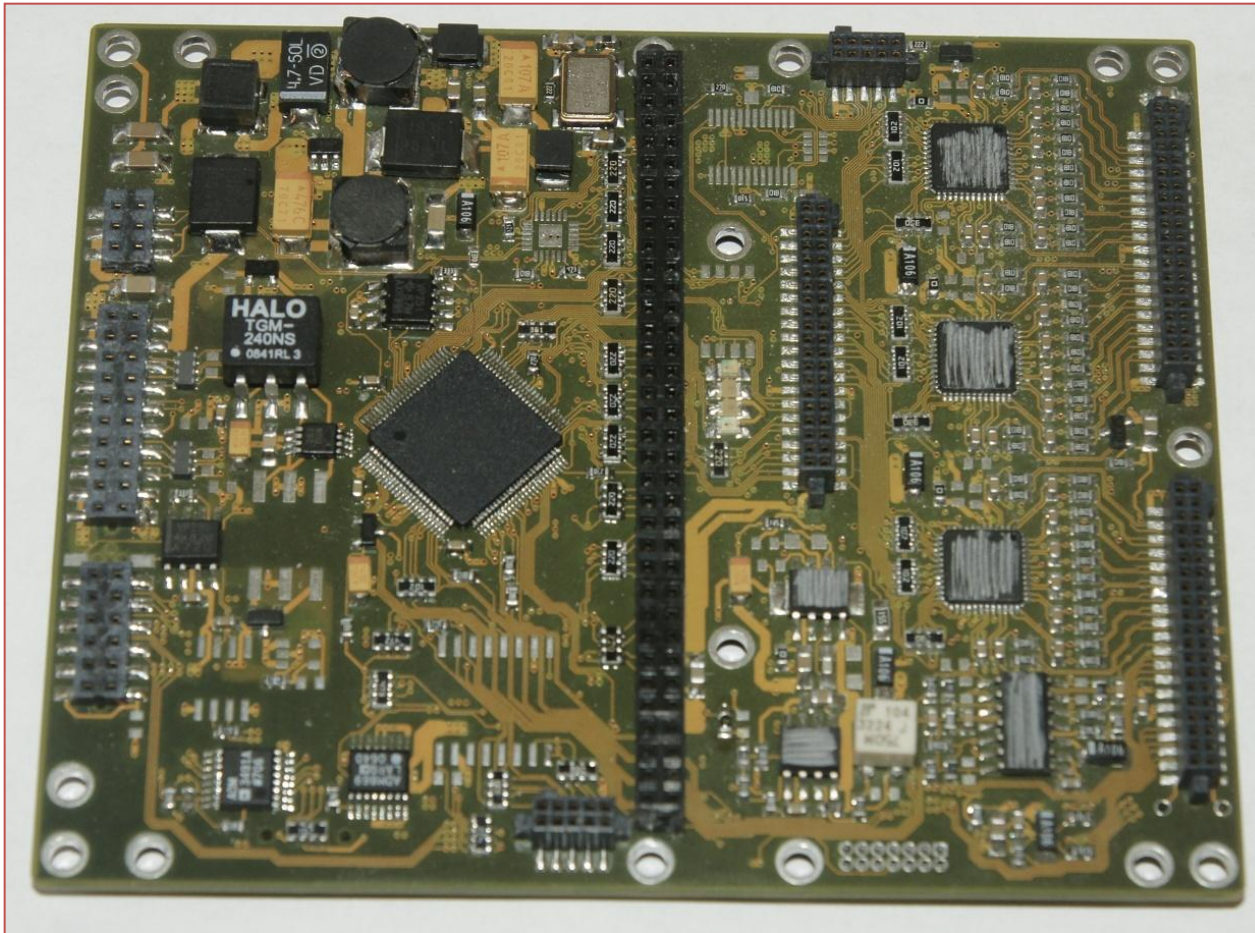
Input Rate Range	$\pm 360$ °/s
Bias	$\leq 0.8$ °/hr
Bias Stability	0.03 °/hr
Bias Temperature Coefficient	0.001...0.003 (°/hr)/°C typical; 0.01(°/hr)/°C maximum
Angular Random Walk	0.003 °/ $\sqrt{\text{hr}}$
Scale Factor	558140 $\pm$ 990 pulses/revolution
Scale Factor Stability	20 ppm 1 sigma
Scale Factor Linearity	20 ppm 1 sigma
Scale Factor Asymmetry	10 ppm
Sensitive Axis Misalignment Stability	$\pm 10$ arc sec.
Start Time (Warm-up time)	10 seconds maximum

# Quartz accelerometer VQ-3

- Acceleration range:  $\pm 50g$
- Scale factor (SF):  $1.35 \pm 0.13 \text{mA/g}$
- SF stability:  $< 100 \text{ppm}$
- SF temperature sensitivity:  $\pm 150 \text{ppm/deg}$
- SF nonlinearity:  $15 \mu\text{g/g}^2$
- SF temperature hysteresis:  $\pm 50 \text{ppm}$
- Bias (at normal conditions):  $\pm 6000 \mu\text{g}$
- Short term bias stability:  $0.6 \mu\text{g}$  (in lower dynamic range)



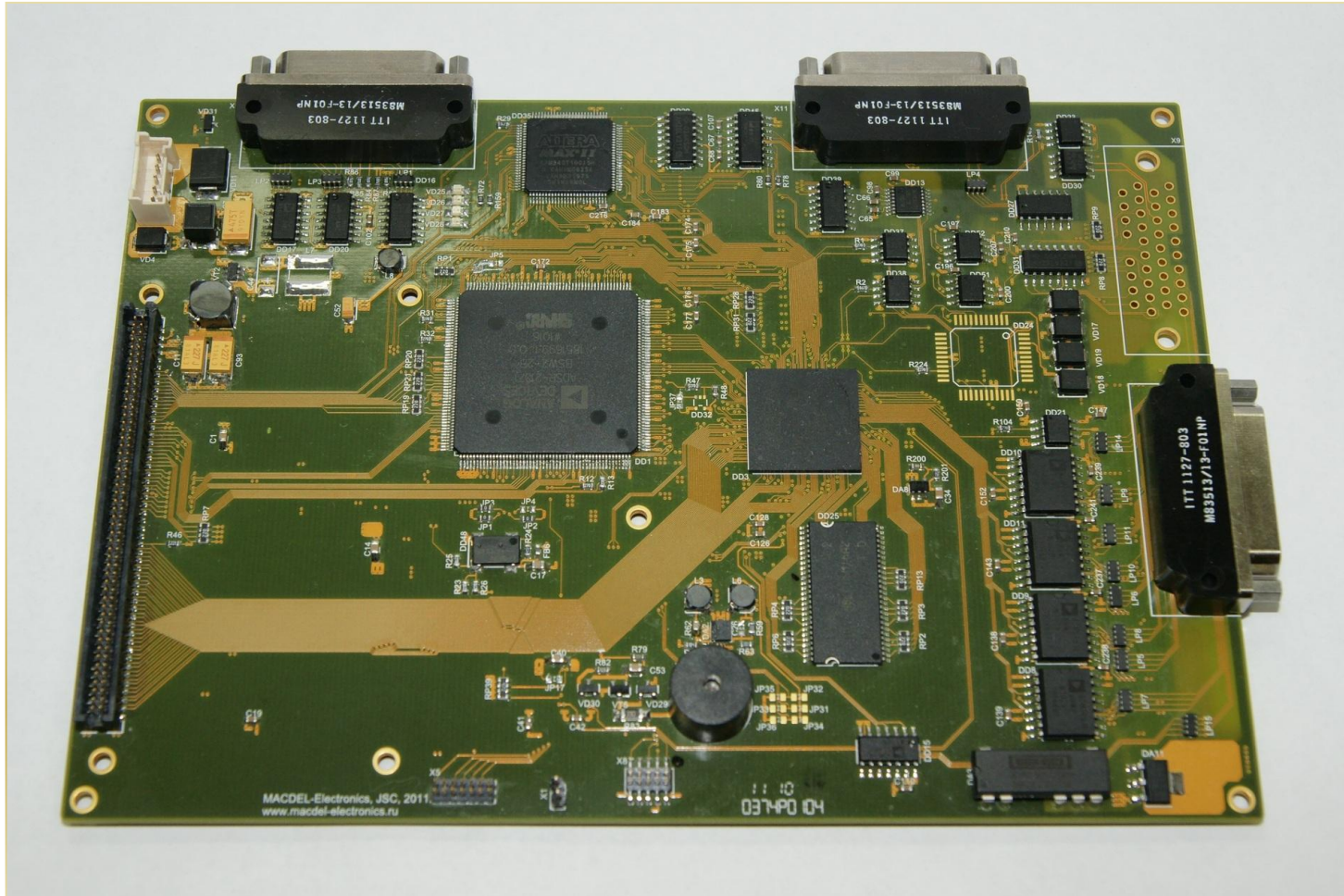
# Digitizer board



3-channel, 24-bit digitizer with 1ppm bias stability in -40...+80deg temperature range.

# SHARC II

## Navigation Processing Module



# SHARC Specification

<b>System</b>	
DSP	Analog Devices SHARC ADSP-21371 @ 333 MHz
External RAM (on board)	SDRAM 8 Mbytes
Flash ROM	4 Mbytes
FPGA	Altera FPGA Cyclone EP3C10F256I7
JTAG	Analog Devices JTAG connector, Altera FPGA JTAG connector for debugging, diagnostics and manufacturing
<b>Interfaces</b>	
2 SHARC on-chip UART, RS-422	For servicing (user software, FPGA project update) and debugging
5 FPGA UART, RS-422	For internal connections to sensors, up to 921600 baud
1 FPGA UART, RS-232	For internal connection to GPS/GLONASS, up to 115200 baud
8 FPGA UART, RS-422, galvanic isolated	For external connections to customer equipment, up to 921600 baud
1 FPGA UART, RS-232, galvanic isolated	For external connections to customer equipment, up to 115200 baud
I/o logical signals	For synchronization, status and control
Expansion connector	For optional interfaces to FPGA
<b>Power, environmental and mechanical</b>	
Power Supply	+12 V, 300 mA ... +24 V, 150 mA (3.6 W)
Temp. range	-40 °C...+85 °C
Dimensions	125 x 175 mm